

# Solutions to Test 1 of

MATH 2202 Linear Algebra I

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$$(1) \begin{bmatrix} 1 & -2 & 3 & 4 \\ 2 & -3 & a & 5 \\ 3 & -4 & 5 & b \end{bmatrix} \xrightarrow[-3R_1+R_3]{-2R_1+R_2} \begin{bmatrix} 1 & -2 & 3 & 4 \\ 0 & 1 & a-6 & -3 \\ 0 & 2 & -4 & b-12 \end{bmatrix}$$

$$\xrightarrow[-2R_2+R_3]{\sim} \begin{bmatrix} 1 & -2 & 3 & 4 \\ 0 & 1 & a-6 & -3 \\ 0 & 0 & 8-2a & b-6 \end{bmatrix}.$$

(i) The system has no solution when  $8-2a=0$  (hence  $a=4$ ) and  $b-6 \neq 0$  (that is  $b \neq 6$ ).

(ii) The system has a unique solution when  $8-2a \neq 0$  (hence  $a \neq 4$ ) and for any value of  $b$ .

(iii) The system has infinitely many solutions if  $8-2a=0$  (hence  $a=4$ ) and  $b-6=0$  (hence  $b=6$ ).

$$(2) \begin{bmatrix} 1 & 3 & 0 & -3 & 8 \\ 2 & 6 & 2 & 9 & 12 \\ 0 & 0 & 1 & 5 & -2 \end{bmatrix} \xrightarrow[-2R_1+R_2]{\sim} \begin{bmatrix} 1 & 3 & 0 & -3 & 8 \\ 0 & 0 & 2 & 15 & -4 \\ 0 & 0 & 1 & 5 & -2 \end{bmatrix}$$

$$\xrightarrow[R_2 \leftrightarrow R_3]{\sim} \begin{bmatrix} 1 & 3 & 0 & -3 & 8 \\ 0 & 0 & 1 & 5 & -2 \\ 0 & 0 & 2 & 15 & -4 \end{bmatrix} \xrightarrow[-2R_2+R_3]{\sim} \begin{bmatrix} 1 & 3 & 0 & -3 & 8 \\ 0 & 0 & 1 & 5 & -2 \\ 0 & 0 & 0 & 5 & 0 \end{bmatrix}$$

(a)  $T$  maps  $\mathbb{R}^5$  onto  $\mathbb{R}^3$  since its standard matrix has a pivot in every row. So columns of  $A$  span  $\mathbb{R}^3$ .

$$(b) A \sim \begin{bmatrix} 1 & 3 & 0 & -3 & 8 \\ 0 & 0 & 1 & 5 & -2 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & 0 & 0 & 8 \\ 0 & 0 & 1 & 0 & -2 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix}.$$

$$x_1 = -3x_2 - 8x_5$$

$$x_3 = 2x_5$$

$$x_4 = 0$$

$x_2, x_5$  are free variables

So

$$X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} -3x_2 - 8x_5 \\ x_2 \\ 2x_5 \\ 0 \\ x_5 \end{bmatrix} = x_2 \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} -8 \\ 0 \\ 2 \\ 0 \\ 1 \end{bmatrix}.$$

$$(c) \quad Ap = \begin{bmatrix} 1 & 3 & 0 & -3 & 8 \\ 2 & 6 & 2 & 9 & 12 \\ 0 & 0 & 1 & 5 & -2 \end{bmatrix} \begin{bmatrix} 6 \\ 1 \\ -1 \\ 0 \\ 7 \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \\ 1 \end{bmatrix}.$$

Parametric equation for solutions of  $Ax=b$  is

$$x = \begin{bmatrix} 6 \\ 1 \\ -1 \\ 0 \\ 7 \end{bmatrix} + r \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + s \begin{bmatrix} -8 \\ 0 \\ 2 \\ 0 \\ 1 \end{bmatrix} \quad r, s \in \mathbb{R}.$$

(d)  $T$  is not 1-1 because the columns of  $A$  are linearly dependent (five vectors in  $\mathbb{R}^3$ ).

$$(3) \quad v = \begin{bmatrix} 1 \\ 3 \end{bmatrix}, \quad u = \begin{bmatrix} h \\ 6 \end{bmatrix}$$

(a)  $b \in \text{span}\{v, u\}$  if  $Ax=b$  with  $A=[v \ u]$  has a solution,  $b = \begin{bmatrix} 4 \\ 8 \end{bmatrix}$ .

$$\begin{bmatrix} 1 & h & 4 \\ 3 & 6 & 8 \end{bmatrix} \sim \begin{bmatrix} 1 & h & 4 \\ 0 & 6-3h & -4 \end{bmatrix}.$$

$Ax=b$  has a solution if  $6-3h \neq 0$  (that is  $h \neq 2$ ).

(b)  $\{v, u\}$  span  $\mathbb{R}^2$  when we have a pivot in every row. This happens when  $h \neq 2$ .

(c)  $\{v, u\}$  are linearly dependent when they are multiple of one another. This happens when  $h=2$ .

$$(4) (a) T \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 + 3x_2 + 2x_3 \\ x_3 \\ 3x_1 + 8x_2 + 3x_3 \end{bmatrix} = \begin{bmatrix} 1 & 3 & 2 \\ 0 & 0 & 1 \\ 3 & 8 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}.$$

So the standard matrix of  $T$  is  $A = \begin{bmatrix} 1 & 3 & 2 \\ 0 & 0 & 1 \\ 3 & 8 & 3 \end{bmatrix}$ .

(b) First find  $A^{-1}$ .

$$\begin{aligned} [A : I_3] &= \begin{bmatrix} 1 & 3 & 2 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \\ 3 & 8 & 3 & 0 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & 2 & 1 & 0 & 0 \\ 0 & -1 & -3 & -3 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 & 0 \end{bmatrix} \\ &\sim \begin{bmatrix} 1 & 3 & 2 & 1 & 0 & 0 \\ 0 & 1 & 3 & 3 & 0 & -1 \\ 0 & 0 & 1 & 0 & 1 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & 0 & 1 & -2 & 0 \\ 0 & 1 & 0 & 3 & -3 & -1 \\ 0 & 0 & 1 & 0 & 1 & 0 \end{bmatrix} \\ &\sim \begin{bmatrix} 1 & 0 & 0 & -8 & 7 & 3 \\ 0 & 1 & 0 & 3 & -3 & -1 \\ 0 & 0 & 1 & 0 & 1 & 0 \end{bmatrix} \end{aligned}$$

So  $A^{-1} = \begin{bmatrix} -8 & 7 & 3 \\ 3 & -3 & -1 \\ 0 & 1 & 0 \end{bmatrix}$ , and  $T^{-1}(x) = A^{-1}x$ . Hence

$$T^{-1} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = A^{-1} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -8x_1 + 7x_2 + 3x_3 \\ 3x_1 - 3x_2 - x_3 \\ x_2 \end{bmatrix}.$$

(5) (a) Since  $A$  is invertible  $AA^{-1} = A^{-1}A = I$ . Hence  
 $I = I^T = (AA^{-1})^T = (A^{-1}A)^T$ . So  $I = (A^{-1})^T A^T = A^T (A^{-1})^T$ ,  
 and hence  $(A^T)^{-1} = (A^{-1})^T$ .

(b) Let  $B = [b_1 \ b_2 \ \dots \ b_n]$ . Then  $AB = [Ab_1 \ Ab_2 \ \dots \ Ab_n]$ .

Let  $\alpha_1 b_1 + \alpha_2 b_2 + \dots + \alpha_n b_n = 0$ , where  $\alpha_i \in \mathbb{R}$ . Then

$$\alpha_1 (Ab_1) + \alpha_2 (Ab_2) + \dots + \alpha_n (Ab_n) = A(\alpha_1 b_1 + \alpha_2 b_2 + \dots + \alpha_n b_n) = A \cdot 0 = 0$$

Since  $[Ab_1 \ Ab_2 \ \dots \ Ab_n]$  are linearly independent,

$\alpha_1 = \alpha_2 = \dots = \alpha_n = 0$ , and hence columns of  $B$  are linearly independent.